Department of Geomatics Engine	eering / Department of Geomatics Engineering / Department of Geomatics Engineering					
Course Code C	ourse Name	Teorical	Practice	Laboratory	Credits	ECTS
GE310 P	HOTOGRAMMETRIC MODELLING	3.00	5.00	0.00	0.00	4.00
Course Detail						
Course Language	: English					
Qualification Degree	: Bachelor					
Course Type	: Compulsory					
Preconditions	: Not					
Objectives of the Course	: The objective of this course is to give basic information about aerial photogram Elevation Model (DEM). Students will have basic knowledge about methodolo production project after taking this courses.					•
Course Contents	: The project processes of the photogrammetric mapping production with aeria flight planning and taking aerial photographs, orientation of aerial photographs photogrammetric mapping, orthophoto and digital elevation models and 3D M	s, aerial triangulation,	-		-	
Recommended or Required Reading	: 1. Kraus, K., Photogrametry Volume 1, Fundamentals and Standard Processes Methods and Applications, Germany, 459 P. 3. Mikhail, E., M., Bethel, S., J., N. 1997. 4. Wolf, P., R., Dewitt, B., A., Elements of Photogrammetry with applicate Range Photogrammetry and Machine Vision, K.B. Atkinson, ISBN:187032446 Principles, methods and applications, Publisher: Whittles, Scotland, Pages: 1	McGlone, J., C., 2001, tions in GIS, 3rd Editio 6X, Whittles Publishin	Modern Photon n, The McGraw g, 1996. 6. Luh	grammetry, Joh /-Hill companie:	ın Wiley-Sons, s, USA, 2000.	USA, 473 P, 5. Close
Planned Learning Activities Teaching Methods	and : Lecture, discussion, exam.					
Recommended Optional Programme Components	: Attandance is important					
Instructors	: Dr. Öğr. Üyesi Serkan Karakış					
Instructor's Assistants	: None					
Presentation Of Course	: face to face					
En Son Güncelleme Tarihi:	:					

Course Outcomes

Upon the completion of this course a student :

1 Defines the photogrammetric map production process.

2 Learn the parameters of flight planning for aerial image recording.

 $3\ \mbox{Students}$ learn how to generate topographic maps and 3D modeling with UAV data.

 $4\,Students\,learn\,how\,to\,callibrate\,the\,camera\,and\,how\,to\,create\,3D\,modeling\,with\,close-range\,photogrammetry$

5 Using advanced photogrammetric technologies (LIDAR) to create maps $\,$

Preconditions

Course Code Course Name Teorical Practice Laboratory Credits ECTS					
		Teorical	Practice		ECTS

Weekly C	ontents					
	Teorical	Practice	Laboratory	Preparation Info	Teaching Methods	Course Learning Outcomes
1.Week	*Temel tanım ve kavramlar					
2.Week	*Hava fotoğraflarının çekimine ilişkin uçuş planlaması ve uçuş yönetimi					
3.Week	*Fotogrametrik nirengi dengelemesi ve hata teorisi					
4.Week	*Lidar teknolojisi ve harita üretimi					
5.Week	*Lidar teknolojisi ve harita üretimi					
6.Week	*Fotogrametrik yöntemle harita yapımı projeleri					
7.Week	*ara sınav					
8.Week	*Fotogrametrik yöntemle harita yapımı projeleri					
9.Week	*Fotogrametrik yöntemle harita yapımı projeleri					
10.Week	*Fotogrametrik yöntemle harita yapımı projeleri					
11.Week	*Mini proje 1					
12.Week	*Sunumlar					
13.Week	*Mini proje 2					
14.Week	*Sunumlar					

1 Final : 40.000	
2 Project : 30.000	
3 Mdterms : 30.000	

Activities Count Time(Hour) Sum of Workload Vize / Midterms 1 1.00 1.00 Final / Final 1 2.00 2.00 Derse Katılım / Attending lectures 14 3.00 42.00	
Final / Final 1 2.00 2.00 Derse Katılım / Attending lectures 14 3.00 42.00	
Derse Katılım / Attending lectures 14 3.00 42.00	
Ara Sınav Hazırlık / Preparation for midterm 1 5.00 5.00	
Final Sınavı Hazırlık / Preparation for final 1 0.00 10.00	
Proje / Project 2 14.00 28.00	
Ders Öncesi Biresysel Çalışma / Individual study before lecture 14 1.00 14.00	
Ders Sonrası Biresysel Çalışma / Individual study after lecture 14 2.00 28.00	

Total: 130.00

Sum of Workload / 30 (Hour): 4

ECTS: 4.00

Program And (OutcomeRelation										
	P.O. 1	P.O. 2	P.O. 3	P.O. 4	P.O. 5	P.O. 6	P.O. 7	P.O. 8	P.O. 9	P.O. 10	P.O. 11
L.O. 1	5	5	0	0	0	5	0	0	0	0	0
L.O. 2	5	5	5	0	0	0	0	0	0	0	0
L.O. 3	4	5	5	0	0	0	0	0	0	0	0
L.O. 4	5	5	0	0	0	5	0	0	0	0	0
L.O. 5	5	5	0	0	0	5	0	0	0	0	0